

Amendments to the Claims

This listing of claims will replace all prior versions and listings of claims in the application:

Claim 1 (withdrawn): An automatic louver actuating system, comprising:

- a plurality of louvered panels, wherein each louvered panel comprises a plurality of louvers capable of rotational movement;
- a plurality of motors, wherein each motor controls the rotational movement of a panel of louvers; and
- a control module, wherein the control module is in communication with each motor.

Claim 2 (withdrawn): The automatic louver actuating system of claim 1, wherein the motor includes an encoder.

Claim 3 (withdrawn): The automatic louver actuating system of claim 1, wherein the communication is infrared.

Claim 4 (withdrawn): The automatic louver actuating system of claim 1, wherein the communication is ultrasonic.

Claim 5 (withdrawn): The automatic louver actuating system of claim 1, wherein the communication is radio waves.

Claim 6. (withdrawn): An electronic louver actuating system, comprising

- a plurality of frames, wherein each frame defines an interior region;
- a plurality of slats rotatably disposed within each interior region of the plurality of frames;

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a plurality of electronic actuating devices, wherein each electronic actuating device is capable of rotating the plurality of slats within each of the plurality of frames; and

a control module, wherein the control module is in communication with each electronic actuating device.

Claim 7 (withdrawn): The automatic louver actuating system of claim 6, wherein the electronic actuating device includes an encoder.

Claim 8 (withdrawn): The automatic louver actuating system of claim 6, wherein the communication medium is infrared.

Claim 9 (withdrawn): The automatic louver actuating system of claim 6, wherein the communication medium is ultrasonic.

Claim 10 (withdrawn): The automatic louver actuating system of claim 6, wherein the communication medium is radio waves.

Claim 11 (currently amended): A method of electronic louver actuating, comprising:

communicating to a first motor a first desired position for a first set of louvers in a first louvered panel;

communicating to a second motor a second desired position for a second set of louvers in a second louvered panel;

rotating the first set of louvers in the first louvered panel to the first desired position by the first motor; and

rotating the second set of louvers in the second louvered panel to the second desired position by the second motor.

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Claim 12 (original): The method of claim 11, wherein the first motor uses an encoder.

Claim 13 (original): The method of claim 11, wherein the second motor uses an encoder.

Claim 14 (withdrawn): An automatic louver actuating system, comprising:

 a first louvered panel, wherein the first louvered panel comprises a first plurality of louvers capable of rotational movement;

 a second louvered panel, wherein the second louvered panel comprises a second plurality of louvers capable of rotational movement;

 a first motor, wherein the first motor controls the rotational movement of the first plurality of louvers;

 a second motor, wherein the second motor controls the rotational movement of the second plurality of louvers; and

 a control module, wherein the control module communicates with the first and second motors.

Claim 15 (withdrawn): The automatic louver actuating system of claim 14, wherein the communication medium is wireless.

Claim 16 (currently amended): A method of controlling a plurality of louvered panels, comprising,

 selecting a louvered panel to rotate;

 storing information representing the selected louvered panel;

 selecting a desired rotation for the louvered panel;

 storing information representing the selected desired rotation; and

 transmitting the information representing the selected desired rotation and the information representing the selected louvered panel over a wireless communication medium.

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Claim 17 (original): The method of claim 16, wherein the wireless communication medium is infrared.

Claim 18 (original): The method of claim 16, wherein the wireless communication medium is ultrasonic.

Claim 19 (original): The method of claim 16, wherein the wireless communication medium is radio.